APPENDIX



	T Oin	Mode	Type / Load	Function
Connector .	Pin 1	Input	Analog 0-5V	Thermistor Input [FF1]
J1	2	Input	Analog 0-5V	Thermistor Input [FF2]
J1	3	Input	Analog 0-5V	Thermistor Input [FZ]
J1	4	Input	Analog 0-5V	Thermistor Input [EVAP]
J1 1	5	Input	Analog 0-5V	Thermistor Input [Pan]
		Input	Digital 0-5V	Personality Input
<u>J1</u>	6	Input	Digital 0-5V	Personality Input
J1 J1	8	Output	5V Power supply	Reference for Thermistors
J1	9	NC	NC	NC

Table 2. J2 Definition, Fan Control

	Pin	Mode	Type / Load	Function
J2	1	Input	Digital 0-12V	RPM Input [Evap]
J2	2	Input	Digital 0-12V	RPM Input [Cond]
J2	3	Power	Digital 0V - Hi Z / 850 mA	Motor Common [Evap & Cond]
<b>J</b> 2	4	Output	Analog 0-12V / 425 mA	Fan Drive Voltage [Evap]
J2	5	Output	Analog 0-12V / 425 mA	Fan Drive Voltage [Cond]
<b>J</b> 2	6	Output	Digital 0V – Hi Z / 200 mA	Low Active Fan Ouptut [FF]
J2	7	Output	Digital 0V – Hi Z / 200 mA	Low Active Fan Ouptut [Pan]
J2	8	Power	12V Power supply / 400 mA	Power For Low Active Fans [FF & Pan]

Table 3. J3 Definition, Encoders and Mullion Damper

	(abio or as			Cunction
0	Pin	Mode	Type / Load	Function
Connector J3	1	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 2)
J3	2	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity

۸.1



Connector	Pin	Mode	Type / Load	Function
Connector				of pin 1)
J3	3	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 4)
J3	4	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 3)
J3	5	Input	Digital 0-5V	Encoder Drive [FF]
J3	6.	Input	Digital 0-5V	Encoder Drive [FZ]
<b>J</b> 3	7	Output	Digital 0-5V	Encoder Input [Bit 3]
<b>J</b> 3	8	Output	Digital 0-5V	Encoder Input [Bit 2]
J3	9	Output	Digital 0-5V	Encoder Input [Bit 1]
J3	10	Output	Digital 0-5V	Encoder Input [Bit 0]

Table 4. J4 Definition, Communications

Connector	Pin	Mode	Type / Load	Function
J4	1	Input / Output	Digital 0-5V	Serial Communication Stream
J4	2	Output	12V Power supply / 1.25 A	Power for Temperature Control and Dispenser Boards
J4	3	Output	DC Common / 1.25 A	DC Common (Not connected to earth ground)
J4	4	Input	Digital 0-12V	Dumb Dispenser Status Input
J4	5	Input	Digital 0-12V	Dumb Dispenser Status Input

Table 5. J5 Definition, Pan Damper Control

Connector	Pin	Mode	Type	Function
J5	1	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 2
<b>J</b> 5	2	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 1
J5	3	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 4
J5	4	Output	Digital 0-12V / 300 mA	Damper Drive Opposite of Pin 3

Table 6. J6 Definition, Flash Programming

0	Pin	Mode	Type	Function
Connector		Output	5 Volt Power	Power Supply
<b>J</b> 6	1	Curpur	Supply	Output
		Output	DC Common	DC Common
J6	2	Output		(Not connected
				to earth ground)
		Input	Digital 0-5V	Serial Data
<b>J</b> 6	3	l "ipat		Received
		Output	Digital 0-5V	Serial Data
J6	4	Cutput	g	Transmitted
		NC	NC ·	NC .
J6	5	NC NC	NC	NC
J6	6	Input	12 Volt Power	VFPP
J6	7	in put	Input	
		Input	Digital 0-5V	Test Pin
J6	8	Input	Digital 0-5V	P19
J6	9	Input	Digital 0-5V	Reset
J6	10	NC	NC	NC
J6	11	NC NC	NC	NC
J6	12		DC Common	DC Common
J6	13	Output	) Do ociminan	(Not connected
		Ì	1	to earth ground)
		- Input	DC Common	DC Common to
J6	14	Input	00000	Select
	ł			Programming
	İ		l	Mode

Table 7. J7 Definition, AC Loads

	Pin	Mode	Type / Load	Function
Connector J7	1	Output	117VAC Line / 4 A	Auger Drive Relay Connects to Pin 4 of This Connector
J7	2	Output	117VAC Line / 0.3 A	Crusher Drive
<b>J</b> 7	3	Output	117VAC Line / 0.5 A	Water Valve Drive
J7	4	Input	117VAC Line / 4.3 A	Auger Drive Relay Connects to Pin 1 of This Connector
J7	5	Output	117VAC Line / 200 mA	Thaw Heater Power
J7	6	Input	117VAC Line	Fresh Food Door
J7	17	Input	117VAC Line	Freezer Door
J7 J7	8 9	NC Input	117VAC Neutral	Return for Door Detection Circuits

#### J8 Definition, Compressor Run

	Pin	Mode	Type / Load	Function
Connector	Fut		117VAC Line / 3	Compressor Run
J8	[1	Output	A TOTAL CANON	Relay

#### Table 9. J9 Definition, Defrost

Otot	Pin	Mode	Type / Load	Function
J9	1	Output	117VAC Line / 6.4 A	Defrost Run Relay
	_1			

## Table 10. J11 Definition, Line Input

	,			
Commenter	Pin	Mode	Туре	Function
Connector	FIII	Input	117VAC Line	Line Input
J11		1 input		

## Table 11. J12 Definition, Pan Heater

	, labie	•••		
	Pin	Mode	Type	Function
Connector			117VAC Line /	Pan Heater
J12	1	Output	0.5 A	Relay Output
	_l	l	10.0 //	

# Table 12 Set Points Associated With Various LEDs

		e 12 Set 1 om 6	ВР	20	Quantum	
PLATFORM	Leap	Frog			Fresh	Freezer
LED	Fresh Fleezer Food (Degrees F) Food (Degrees F)		Freezer (Degrees F)	Food (Degrees F)	(Degrees F)	
	(Degrees F)	Off	Off	Off	Off	Off
0	Off	6	46	6	45	66
1 - Warmest	45	4	41	3	40	4
2	40	40	39		39	3
3	-39	3		1	38	1
4	38	1	38	0	37	0
5	37	0	37	-1	36	-1
6	36	-1	36		35	-3
7	35	-3	. 35	-1	35	4
8	35	-4	35	4		-6
9- Coldest	34	-6	34	6	34	1

Table Danie and order								
FZ	FF	Mode	Com					
Display	Display_							
0	1	HMI to Main Control	The Turbo Cool LED will light up confirming					
		Communications	communication between the two boards.					
0	.2	HMI to Dispenser	The Turbo Cool LED will light up confirming					
		Communications	communication between the two boards.					
0	3	Dispenser to Main Control	The Turbo Cool LED will light up confirming					
		Communications	communication between the two boards.					
0	4	Encoder Test	As the encoders are rotated, the test mode will stop					
			flashing and the corresponding setting of the encoder					
			will appear on the freezer display of the HMI.					
0	5	HMI Self Test	See below					
0	6	Control and Sensor System	See below					
		Self Test						
0	7	Open Duct Door	Duct Door will open for 10 seconds and then close					
0	8	Sweat Heater Test	Turn the sweat heater on for 60 seconds					
0	9	Open Dampers	Each Damper will open, pause briefly, and then close					
1	0	Fan Speed Test	Each fan will run for 30 seconds at low speed, then					
_	i		for 30 seconds at medium speed, and finally for 30					
]			seconds at high speed.					
1	1	100% Run Time	This mode runs the sealed system 100% of the time.					
ļ -	1	1	This will automatically time out after 1 hour of run					
}			time.					
1	2	Enter Prechill	This places the freezer in prechill mode. It will					
_	-		return to normal operation on its own.					
ī	3	Enter Defrost	This will set the refrigerator into defrost mode. It					
]	-		will return to normal operation on its own. If the					
			cavity is not cold when this mode is executed, it may					
			execute extremely fast.					
1	4	Refrig	Causes a system reset.					
1	5	Test Mode Exit	Causes a temperature board reset					

iau ie		· · · · · · · · · · · · · · · · · · ·
<u>Device</u>	<u>Detection</u>	Strategy
FZ Thermistor	• FZ Thermistor Circuit OPEN	<ul> <li>Set FZ unfittered temp = -40, ensuring unigrid bottom row (X,W,V,U,T,S) execution.</li> <li>EFOSSO disabled.</li> </ul>
FF1 or FF2 Thermistor (Quantum)	FFx Thermistor Circuit OPEN	Quantum only - Disregard out of range FFx temp. In the FF avg. temp. calculation.
FF1 and FF2 Thermistor (or BPO, Leap single FF thermistor)	FF1 Thermistor Circuit OPEN, AND     FF2 Thermistor Circuit OPEN	<ul> <li>Set FF no freeze &lt; FF avg. unfittered temp &lt; FF low hysteresis, ensuring unigrid (E,K,Q,W) column execution.</li> </ul>
Damper Operation	<ul> <li>Damper commanded open, but FF avg temperature increases &gt; 0.3F in 5 min.</li> <li>Damper commanded closed, but FF avg temperature decreases &gt; 0.3F in 5 min.</li> </ul>	Send appropriate command again to damper (open/close)
Evap. Thermistor	Evap. Thermistor Circuit OPEN	Defrost operation occurs as follows: defrost duration of 20 minutes, dwell duration of 5 minutes, and 8 hours of compressor run time elapses between defrosts.
Evap. Fan	No RPM feedback	Operate evaporator fan at 100% duty cycle.
Power Line Fault	None	<ul> <li>Store defrost state and defrost timer status every 30 minutes or upon defrost state change.</li> <li>Algorithm uses saved state and timer values if FZ temp &lt; Defrost termination temp.</li> <li>Algorithm reinitializes state and timer values if FZ temp &gt;= Defrost termination temp.</li> </ul>

Table /5 Control Board Commands

Add- ress	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x01	Firmware Version	<3 byte ascii version>	
0x10	0x61	Monogram Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x62	Feature Pan Damper 1 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x63	Feature Pan Damper 2 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x64	Feature Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x65	Damper Control		Open if Data = 0x51 and Close if Data = 0x41

		Tail continued		
Add-	Com.	Command Received	Communication	Physica sponse
ress	Byte		Response	
0x10	0x66	Start/Stop Condenser		0x41=Off,
OXIO	OXOO	Fan		0x51=On
0x10	0x67	Start/Stop Evaporator		0x00=Off,
ן טיגט	OXO7	Fan (Variable Speed)		0x01=Low,
	l	Tan (vaniable op-		0x02=Med,
		i		0x03=High
- 10	0x68	Start/Stop Fresh Food		0x00=Off,
0x10	UXO8	Fan (Variable Speed)	ł	0x01=Low,
		Pall (Variable opera)		0x02=High
	0.00	Start/Stop Turbo		Start If Data =
0x10	0x69	Mode Mode	į	0x51 and Stop If
		Mode	_	Data = 0x41
		Start/Stop Feature		Chill Pan Fan
0x10	0x6A	Pan Fan (Variable		Starts With Data
	1	Speed)		Value Setting
	1	Speed)		Speed
		G L For Speed	1 Bytes	
0x10	0x6B	Condenser Fan Speed	0x51=On, 0x41=Off	·
		Request	2 Bytes	0x41=Logical
0x10	0x6C	Evaporator Fan	For Logical: 0=Off,	State, 0x51=RPM
		Speed Request	1=Low, 2=Med,	
	1		3=High	
	1		1 Byte	
0x10	0x6D	Fresh Food Fan	0=Off, 1=Low,	
	ł	Speed Request	0=011, 1=25w, 2=High	
			1 Byte	
0x10	0x6E	Feature Pan Fan	0x51=On, 0x41=Off	
		Speed Request	0x51=011, 0x41=011	One Data Byte with
0x10	0x70	Dispense		masks for each
ł	Ì	1		selection
]	ļ			Water = 0x01
ì	1	ł		Cubed =0x02
1				Crushed = $0x04$
				Engage If Data =
0x10	0x71	Engage Water Valve	{	0x51 and Release
1	1	1	,	If Data = $0x41$
L			<del> </del>	Energize If Data =
0x10	0x72			0x51 and Release
1	1	Heater		If Data = $0x41$
<b>!</b>				Energize If Data =
0x10	0x73			0x51 and Release
	1	. Motor		If Data = $0x41$
1			<del></del>	Start If Data =
Ox1	0 0x74	Start Compressor		0x51 and Stop If
				Data = 0x41
1	1			Energize If Data =
Ox1	0 0x7	5 Energize Crusher	1	0x51 and Release
		Bypass Solenoid		If Data = 0x41
1	1			
<del>                                     </del>	0 0x7	6 Read Sealed System	2 Bytes < Minutes of	
0x1	U 1 UA1		ON Time>	

0x10

Table/4 tinued Physical Response Communication Command Received Com. Add-Response Byte ress 2 Bytes < Minutes of Read Sealed System 0x77 0x10 OFF Time> **OFF** Time 0x41 = Inst. Value 2 Bytes Read FF Thermistor 0x80 0x10 0x51 = FilteredTemp X 100 or the 1 0x61=Unamp. A/D Counts 0x71=A/D Counts 0x41 = Inst. Value 2 Bytes Read FF Thermistor 0x81 0x10 0x51 = FilteredTemp X 100 or the 0x61=Unamp. A/D Counts 0x71=A/D Counts 0x41 = Inst. Value2 Bytes Read FZ Thermistor 0x10 0x82 0x51 = FilteredTemp X 100 or the 0x61=Unamp. A/D Counts 0x71=A/D Counts 0x41 = Inst. Value2 Bytes Read Evaporator 0x83 0x10 0x51 = FilteredTemp X 100 or the Thermistor 0x61=Unamp. A/D Counts 0x71=A/D Counts 0x41 = Inst. Value2 Bytes Read Feature Pan 0x10 0x84 0x51 = FilteredTemp X 100 or the Thermistor 0x61=Unamp. A/D Counts 0x71=A/D Counts 0x41 = Inst. Value2 Bytes Read Ambient 0x10 0x85 0x51 = FilteredTemp X 100 or the Thermistor 0x71=A/D Counts A/D Counts 4 Bytes: Get Number of Door 0x86 0x10 FZ MSB, FZ LSB, **Openings** FF MSB, FF LSB Reset Door Openings 0x87 0x10 Counter <State of Various Read Sensors 0x10 0x88 Sensors -> 1 byte> 6 Bytes: Read Dispense 0x89 0x10 Water MSB, Water Counters LSB, Cubed MSB, Cubed LSB, Crushed MSB, Crushed LSB 0 = OffEnter Feature Pan Ox8A 0x10 1 = Small Pkg. Defrost Mode 2 = Med. Pkg.3 = Lg. Pkg.0 = OffEnter Feature Pan 0x10 0x8B 1 = 15 min.**Quick Chill Mode** 2 = 30 min. $3 = 45 \, \text{min}$ Reset Dispense 0x8C 0x10 Counters Reset Freshness Filter 0x90 0x10 Timer Reset Water Filter 0x91

Timer

Table /5 continued Physical esponse Communication Add-Com. Response Byte ress Memor ointer is Set EEPROM Read 0xA0 0x10 set for next Address Diagnostic eeprom read sequence. Memory read 0xA1 Set EEPROM Read 0x10 length is set for Length next Diagnostic eeprom read sequence. Read EEPROM <EEPROM Data 0x10 0xA2 defined by previous two commands> First two data bytes Write EEPROM 0x10 0xA3 define the eeprom address, bytes three and four are the data written to that 16 bit area. <Set Point Read Set Points 0x10 0xA4 Temperatures from EEPROM (First Byte is FF, Second Byte is FZ)> Send Set Points to Write Set Points 0x10 0xA5 EEPROM (First Byte is FF, Second Byte is FZ) 0xB0 Check Refrigerator <State of 0x10 Status Refrigerator> Perform FF Fan 1 = Fan OK 0xB1 0x10 2 = Fan Missing or Diagnostics Open 3 = Fan Shorted4 = Fan Stalled Perform Evap Fan 1 = Fan OK 0x10 0xB2 **Diagnostics** 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled 5 = Blade Missing 1 = Fan OK 0x10 0xB3 Perform Cond Fan 2 = Fan Missing or **Diagnostics** Open 3 = Fan Shorted 4 = Fan Stalled Perform Feature Fan 1 = Fan OK 0x10 0xB4 2 = Fan Missing or **Diagnostics** Open 3 = Fan Shorted 4 = Fan Stalled 2 Bytes <Status of Status of Outputs 0xB5 0x10

digital I/O>

Γ	Add-	Com.	Command Received	Communication	Physical Response
ŀ	-1CSS	-Byte	-	Response	
	0x10	0xBA	Get Encode tings	2 Bytes: FF Setting, FZ Setting	
t	0x10	0xBC	Get Model Inputs	1 Byte with value of model inputs	
1	0x10	0xC0	Enter Diagnostic Mode		All outputs are off or closed
Ì	0x10	0xC1	Exit Diagnostic Mode		Will reset refrigerator
ł	0x10	0xF9	Forced Reset		
ı	0x10	0xFA	Forced Prechill		
1	0x10	0xFB	Forced Defrost		
ı	0x10	0xFC	100% Run		ļ
1	0x10	0xFD	Disable defrost		ļ
	0x10	0xFE	Calibrate thermistor channels against known resistance		

Bit 128	Bit 64	Bit 32	Bit 16	Bit 4	Bit 2	Bit 2	Bit 1
0	0	FF Door	FZ Door	0	0	0	0

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
0	FF	FZ	Water	Auger	State	Crush	Mongr.	Defrst	
	Door	Door	Disp.	State	of	Sol.	Heater	Heatr	
	Sensr	Sensr	Valve	1	Com-	State	•	State	
*			State		press				
1	Damp.	Feat.	Feat.	Feat.	Feat.	Cond	FF Fan	0	
	State	Pan	Pan	Pan	Pan	Fan		<u> </u>	
		Damp.	Damp.	Heatr.	Fan				
		1 State	2 State	<u> </u>	<u> </u>	<u> </u>	<u> </u>	L	
2	FF1 Ten	np MSB							
3	FF1 Ten	np LSB							
4	FF2 Ter	np MSB							
5	FF2 Ter	np LSB							
6	FF Aver	age Temp	MSB						
7	FF Ave	rage Temp	LSB						
8	FZ Tem	p MSB							
9	FZ Tem	p LSB							
10	Evap To	emp MSB	· .						
11		Evap Temp LSB							
12	Feature	Feature Pan Temp MSB							
13	Feature	Reature Pan Temp LSB							
14	Evap Fa	an Speed (	0=Off, 1=	Low, 2=M	ed, 3=Hig	<u>h)</u>			

•	190	ie /D		Di micel Bernance
Add- Ress	Com. Byte	Command Received	Communication Response	Physical Response
0x11	0x01	Firmwersion	<3 byte ascii version>	
0x11	0x6F	EEPROM data from mainboard		
0x11	0x90	Set Display		See table below
0x11	0x91	Read Buttons	<pre><state -="" buttons="" of="" various=""> 4 bytes&gt;</state></pre>	
0x11	0x92	Pulse Beeper		
0x11	0xA4	Reply from main with temperature settings		
0x11	0xBA	Reply from main with encoder settings		
0x11	0xC0	Door Open		0x51 = door open 0x41 = door closed
Ox11	0xF2	Temperature to main/dispenser communications test		·
Ox11	0xF3	Dispenser to main communications test		
0x11	0xF4	Open duct door		<u> </u>
0x11	0xF5	Sweat heater test		
0x11	0xF6	Sensor system self- test		
0x11	0xF9	Forced reset		

	lao	le/ 7						77:4
Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Thaw 1	Cool	Lock	Filter	Door	Cube	Crush	Water
1	0	0	0	Chill 3	Chill 2	Chill 1	Thaw 3	Thaw 2
2	Bits 0 -	6, Fresh I	ood LED	0				
3		6, Fresh I						
4		6, Fresh I		2				
5		Bits 0 - 6, Freezer LED 0						
6	Bits 0 - 6, Freezer LED 1							
7	Bits 0 -	6, Freeze	r LED 2					

Table 20

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Lock	Reset Fresh Filter	Fresh Food Dec	Fresh Food Inc	Freezer Dec	Freezer Inc	Defrost / Chill	Turbo Cool
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	Door	Thaw	Light	Cube Key	Water Key	Crush Key

	IONIC			Physical Response
Add-	Com.	Command Received	Communication	Tilysical Response
Ress	Byte		Response	
0x12	0x01	Fire Version	<3 byte ascii version>	
0x12	0x6F	EEPROM data from mainboard		G while below
0x12	0x90	Set Display		See table below
0x12	0x91	Read Buttons	<pre><state -="" buttons="" of="" various=""> 4 bytes&gt;</state></pre>	
0x12	0x92	Pulse Beeper		
0x12	0xA4	Reply from main with temperature settings		
0x12	0xBA	Reply from main with encoder settings		
0x12	0xC0	Door Open		0x51 = door open 0x41 = door closed
0x12	0xF2	Temperature to main/dispenser communications test		
0x12	0xF3	Dispenser to main communications test		
0x12	0xF4	Open duct door	<b></b>	_ <del> </del>
0x12		Sweat heater test		<del></del>
0x12		Sensor system self- test		
0x12	0xF9	Forced reset		

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Thaw 1	Cool	Lock	Filter	Door	Cube	Crush	Water
1	0	0	0	Chill 3	Chill 2	Chill 1	Thaw 3	Thaw 2
2	Bits 0 - 6, Fresh Food LED 0							

## Table 23

	lan	e $\sigma$ $\sigma$						D:40
Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
3	Bits 0 – 6, Fresh Food LED 1							
4	Bits 0 – 6, Fresh Food LED 2							
5	Bits 0 - 6, Freezer LED 0							
6	Bits 0 – 6, Freezer LED 1							
7	Bits 0 – 6, Freezer LED 2							

Bit 7 Lock	Bit 6 Reset Fresh Filter	Bit 5 Fresh Food Dec	Bit 4 Fresh Food Inc	Bit 3 Freez er Dec	Bit 2 Freez er Inc	Bit 1 Defro st / Chill	Bit 0 Turbo Cool
Bit 7	Bit 6	Bit 5 Door	Bit 4 Thaw	Bit 3 Light	Bit 2 Cube Key	Bit 1 Water Key	Bit 0 Crush Key

Table 25						
Data Name	Length !	Туре	Function			
(Module/Data)		<u> </u>				
All Modules /	1	Char	R = Run I = Initialization			
State Code		<del> </del>	Points to String Where			
Command Processor	1	Structure Pointer	Byte 1 = Command,			
/ Command		j l	Byte 2 = Address,			
		·	Successive Bytes Data			
	ļ. <u>.</u>	Structure Pointer	Points to String Where			
Command Processor	1	Suuciaie i oimes	Byte 1 = Command,			
/ Command (Note:			Byte 2 = Address,			
for received	1		Successive Bytes Data			
commands)	1	Unsigned Char	Bit 0 = Main Valve,			
Dispense /	1	Olbigino -	Bit 1 = Water Valve,			
Command			Bit 2 = Electromagnet,			
1	1		Bit 3 = Auger,			
	1		Bit 4 = Crusher Sol.			
Protocol Data Parse	1	Boolean	True Means Clear			
/ Clr OK	1		Buffer			
/ Cil Ok		l l	False Means Do Not			
			Clear Buffer			
Protocol Data Parse	1	Structure Pointer	Points to String Where Boolean = Rstatus			
/ Command &			(True if			
Rstatus		,	command			
, Kundo			received and			
			CS OK)			
			Byte 1 = Command,			
		,	Byte 2 = Address,			
			Successive Bytes Data			
		Boolean	True if last command			
Protocol Data XMI	T 1	Doolean	was successfully			
/ XMIT Status			transmitted.			
			False if last command			
			did not transmit or is			
	]		still transmitting.			





Table 35 continued							
Data Name (Module/Data)	Length	Туре	Function				
Protocol Data XMIT / Command	1	String Pointer	Points to String Where Byte 1 = Command, Byte 2 = Address, Successive Bytes Data. NOTE: If pointer is NULL, then XMIT Status is returned based on the success or failure of the previous command.				
LED Control / LED Pattern	1	Unsigned Long	Each of the 32 bits corresponds to an LED.				
Keyboard Scan / Key Status & Key Value	1	Unsigned Int.	MSB = Key Status (1=key pressed) Each of the bits beginning with the LSB correspond to a key. If no key is being pressed the contents of the status will reflect the last key combination pressed.				
Protocol Packet Ready / Rstatus	i	Boolean	True if command received and CS OK Else it returns False				
Physical Xmit Char / Char	1	Unsigned Char	Contains character to be transmitted				
Physical Xmit Char / XMIT Status	1	Boolean	True if last command was successfully transmitted. False if last command did not transmit or is still transmitting.				
Xmit Port Avail / xPort Status	1	Boolean	True if port is available. False if port is not available.				
Key Pressed / Key Status	1	Boolean	True if key is pressed. False if key is not pressed.				

	W W			
DayCount	4 Bytes - Counts Days for both Filter Functions			
OneMinute	1 Byte - Set to 60 when initialized. At the minute has passed.			
RXBuffer	16 Bytes - Buffer used to store comm			
Turbo Timer	Unsigned Int – Contains the number of minutes remaining until Turbo Mode times out.			
Chill Timer	Unsigned Int – Contains the number of minutes remaining until Quick Chill Mode times out.			
Daily Rollover	Unsigned Int – Counts minutes each day			

Table 27	·		
Data Name	Length	Туре	Function
All Modules /		Char	R = Run
State Code	•		I = Initialization
State Code			D = Diagnostics
Protocol Data Parse	1	Boolean	True Means Clear
/ Clr OK	•		Buffer
/ CIr OK			False Means Do Not
		·	Clear Buffer
Protocol Data Parse	1	Structure Pointer	Points to String Where
	•		Boolean = Rstatus
/ Command &			(True if
Rstatus			command
			received and
	1	1	CS OK)
		i	Byte 1 = Command,
			Byte $2 = Address$ ,
			Successive Bytes Data
TO VACE	1	Boolean	True if last command
Protocol Data XMIT	1 '		was successfully
/ XMTT Status			transmitted.
			False if last command
	Ì		did not transmit or is
	}	l	still transmitting.
12 30 67	1	String Pointer	Points to String Where
Protocol Data XMIT	1'	022.8	Byte 1 = Command,
/ Command		1	Byte $2 = Address$ ,
Ì		l l	Successive Bytes Data.
			NOTE: If pointer is
	1	· ·	NULL, then XMIT
	-	·	Status is returned based
			on the success or failure
	ŧ		of the previous
	Ì		command.
	1	Unsigned Char	Sensor Number range 1-
Apply Calibration	1.1	O.L.g.	255 -
Constants &		• .	
Linearize / Sensor #	1	signed Int	Temperature in degrees
Apply Calibration	<b>                                   </b>	3.6	Fahrenheit Times 100
Constants &	1		Range -12700 to
Linearize / Value	1.		+12800.
	1	Unsigned Char	Sensor Number range 1-
Read Sensor /	1.	C.D.g.ioc Still	255
Sensor #	<del>-   1</del>	Int	A/D Counts for selected
Read Sensor / A/D	1 1		sensor.
Cnts			